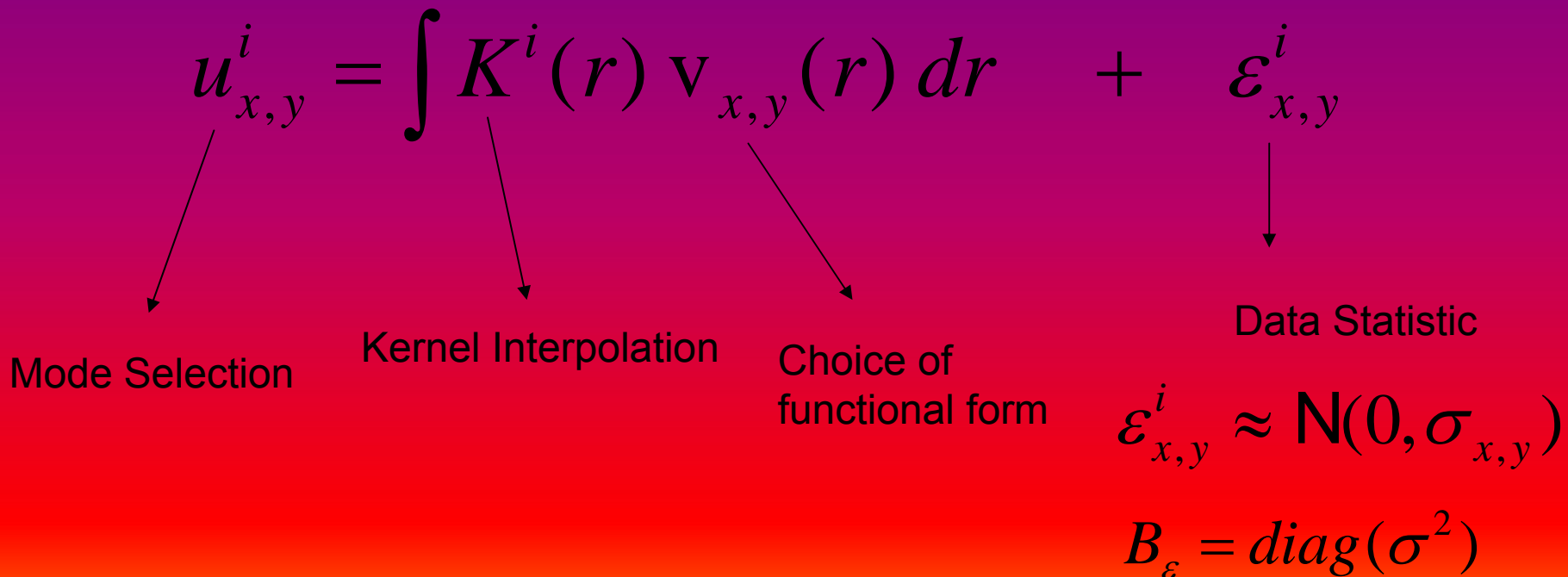


# Inversion for ring diagram analysis in GONG++ Pipeline

- What are we currently doing ?  
RLS inversion and its details
- What could be done?  
Tests with OLA

# The Inverse problem in Ring Diagram Analysis

Ring Fitting  $\Rightarrow (n, \nu) \equiv i$   
 $\{u_x, \sigma_x, u_y, \sigma_y\}_{i=1\dots N}$



# Mode Selection

$(n, \nu, u_x, u_y, \sigma_x, \sigma_y)$  is kept if :

1.  $n^- \leq n \leq n^+$        $n^- = 0$     $n^+ = 6$

2.  $|u_x| < u_{max}$  &  $|u_y| < u_{max}$        $u_{max} = 500 \text{ m/s}$

3. *There exists 2 modes in kernel file such that*

a)  $\max(\nu_{min}, \nu - \delta\nu) < \nu^- \leq \nu \leq \nu^+ < \min(\nu_{max}, \nu + \delta\nu)$        $\delta\nu = 1000 \mu\text{Hz}$   
 $\Rightarrow$  *we exclude the extreme frequencies for each n*

b)  $\ell^- > \ell_{min}$  &  $\ell^+ > \ell_{min}$        $\ell_{min} = 175$

# Kernel Interpolation

We use:

$$v = c\sqrt{l} + b$$

$$\begin{array}{l} (v^+, l^+) \\ (v^-, l^-) \end{array} \longrightarrow C, b$$

$$l = \left( \frac{v - b}{c} \right)^2,$$

$$K = K^- + (K^+ - K^-) \left( \frac{l - l^-}{l^+ - l^-} \right)$$

# RLS Inversion

$$\min \left\{ \sum_i \left( \frac{u^i - \int K^i(r) v(r) dr}{\sigma_i^2} \right)^2 + \lambda \int \left( \frac{\partial^2 v(r)}{\partial r^2} \right)^2 dr \right\}$$

- Choice of regularization: second derivative
- Choice of functional form for  $v(r)$ : step function

$$v(r) = \sum_{j=1}^m v_j(r) \quad v_j(r) = \begin{cases} \bar{v}_j & r_j \leq r < r_{j+1} \\ 0 & \end{cases}$$

$\{r_j\}_{j=1 \dots m+1}$  equally spaced in acoustic radius

$r_1=0.9$

$m=50$

$$\int K^i(r) v(r) dr \approx \sum_j v_j \underbrace{\int_{r_j}^{r_{j+1}} K^i(r) dr}_{\{K_{ij}\}_{i=1\dots N, j=1\dots m}}$$

- Central differences for second derivatives

$$\left( \frac{\partial^2 v}{\partial r^2} \right)_j \approx v_{j-1} - 2v_j + v_{j+1} \quad j=2\dots m-1$$

$$\bar{v} = \arg \min \left( \| B_\varepsilon^{-1/2} (u - K v) \|^2 + \lambda \| L v \|^2 \right)$$

$$L = \begin{pmatrix} 1 & -2 & 1 & 0 & 0 & \dots \\ 0 & 1 & -2 & 1 & 0 & \dots \\ 0 & 0 & 1 & -2 & 1 & \dots \\ 0 & 0 & 0 & \ddots & \ddots & \ddots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{pmatrix}$$

# Diagnostic Tools

$$u = K v + [\varepsilon]$$

$$\bar{v} = \underbrace{\left( K^T B_u^{-1} K + \lambda L^T L \right)^{-1} K^T B_u^{-1} u}_A$$

$$\Rightarrow \bar{v} = \underbrace{A K}_{\text{Resolution matrix}} v + A[\varepsilon]$$

*Resolution matrix*

$$\bar{v}_j = \int \underbrace{\sum_i A_{ji} K^i(r)}_{K_j(r)} v(r) dr$$

**Resolution Kernel**

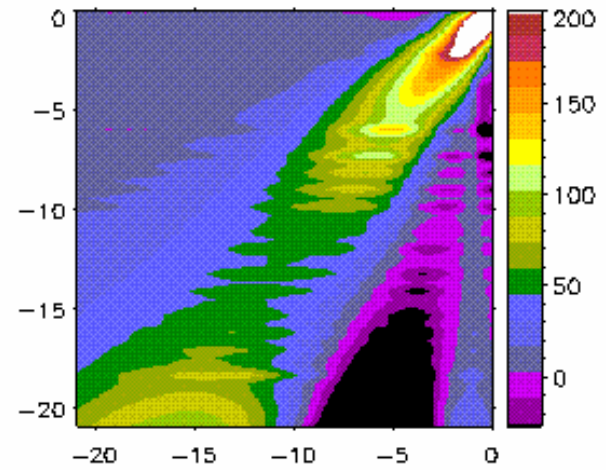
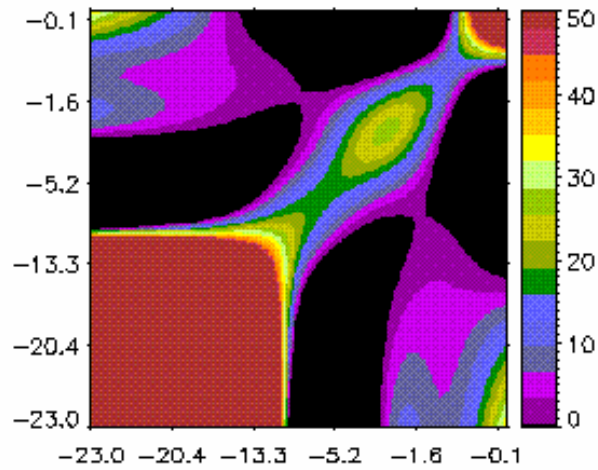
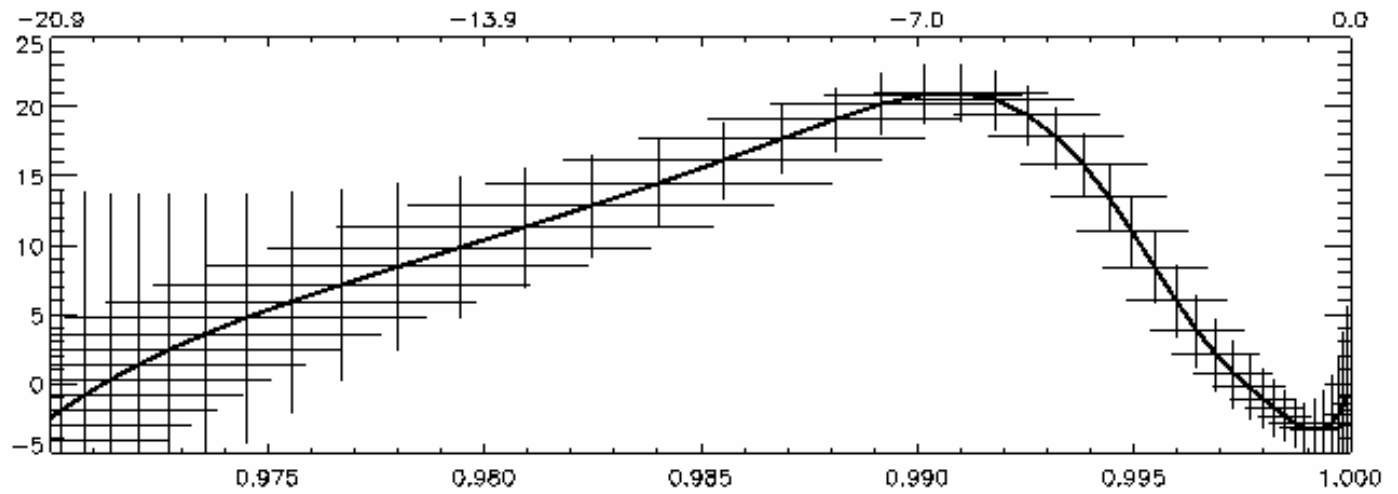
$$\chi^2 = \frac{\| B_\varepsilon^{-1/2} (u - K \bar{v}) \|^2}{N - m}$$

**Chi-square value**

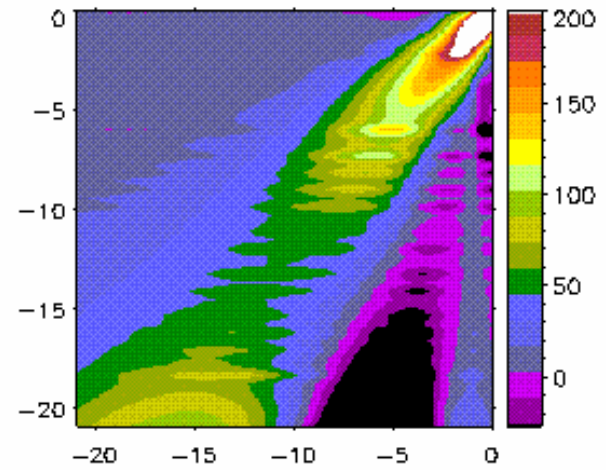
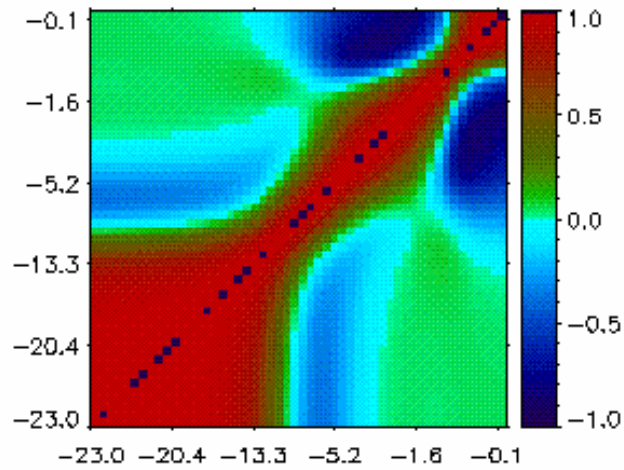
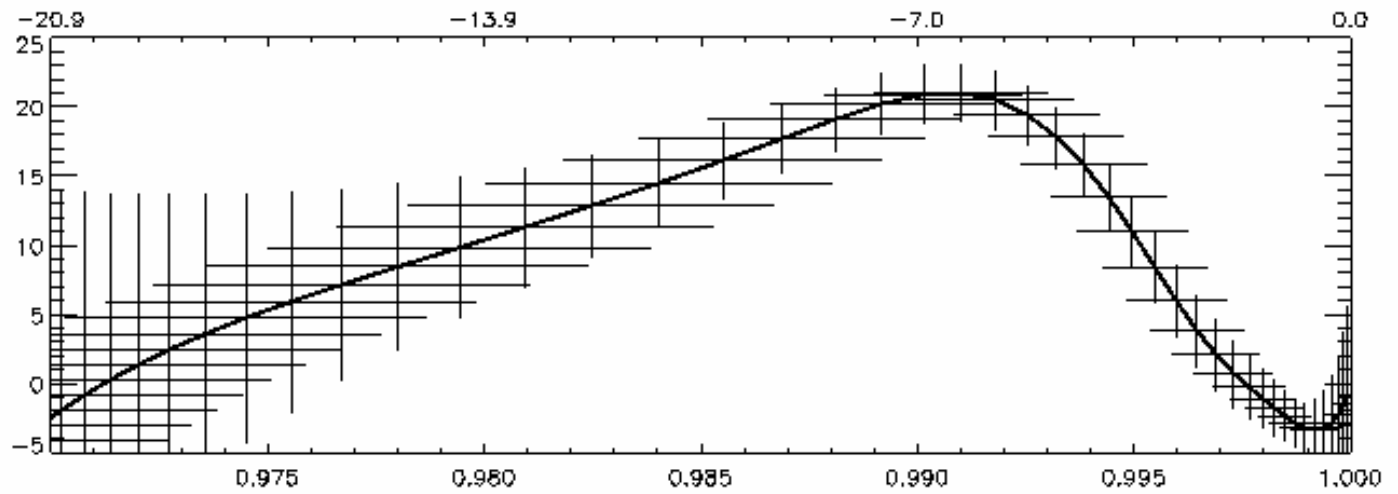
$$B_{\bar{v}} = A B_\varepsilon A^T$$

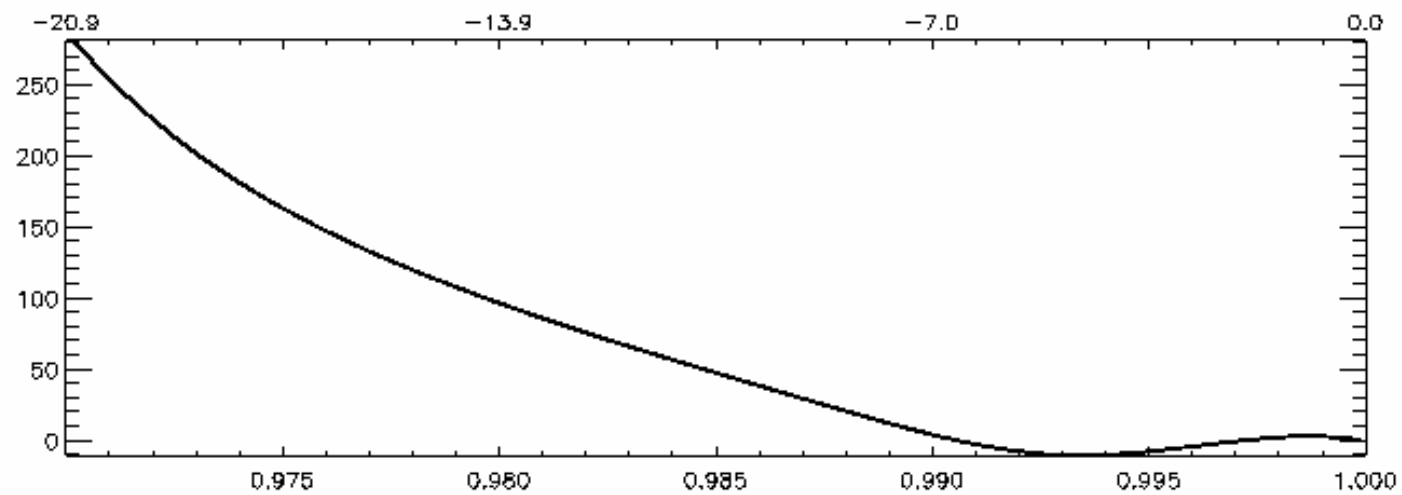
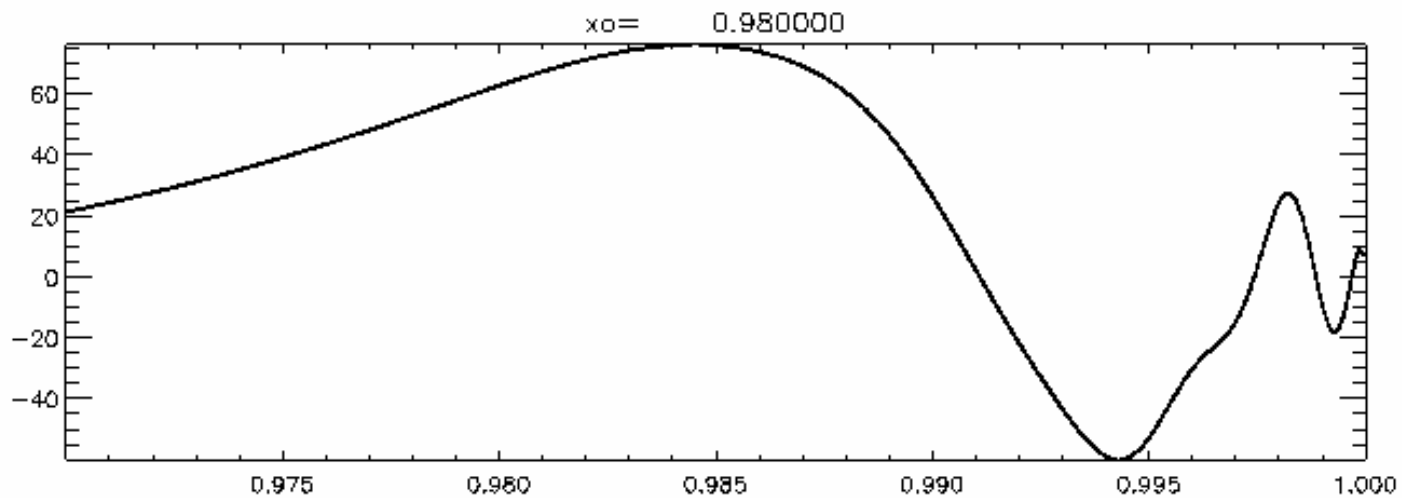
**Covariance Matrix**

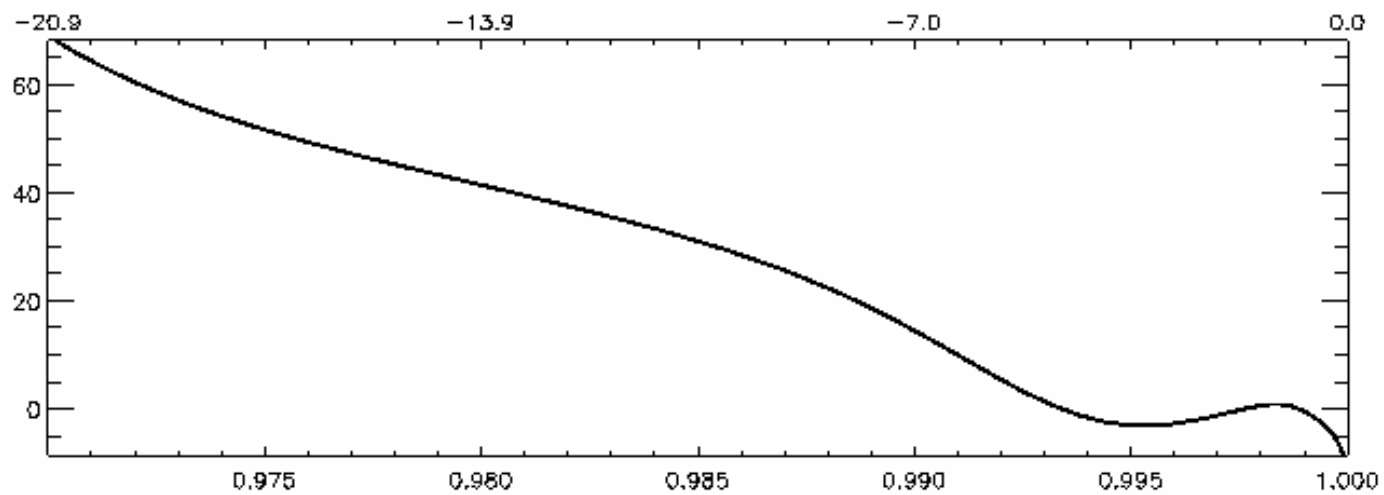
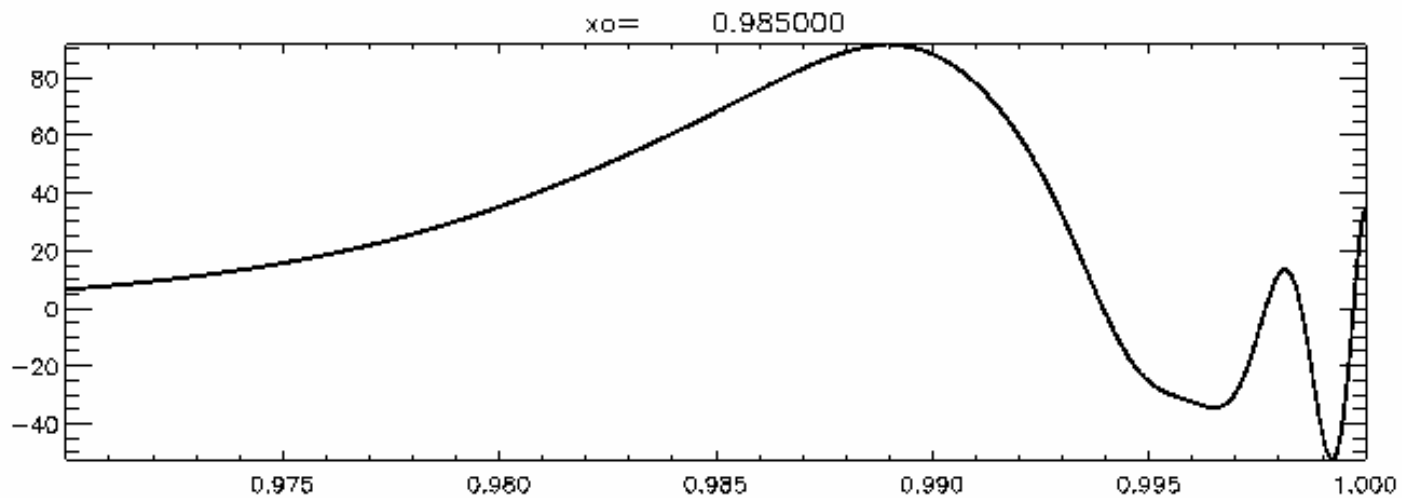


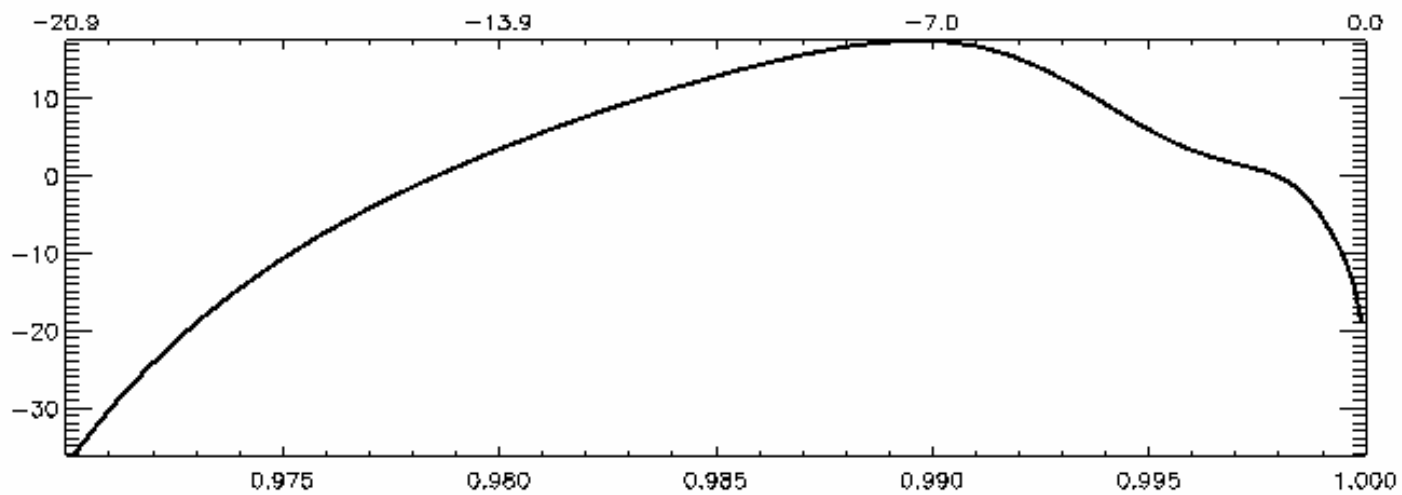
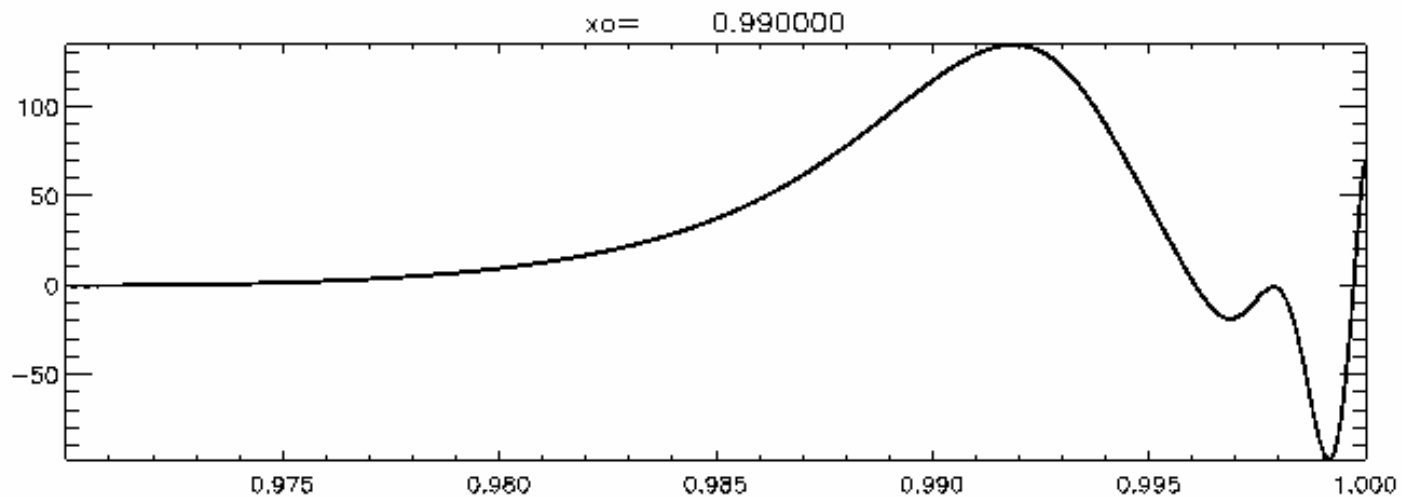


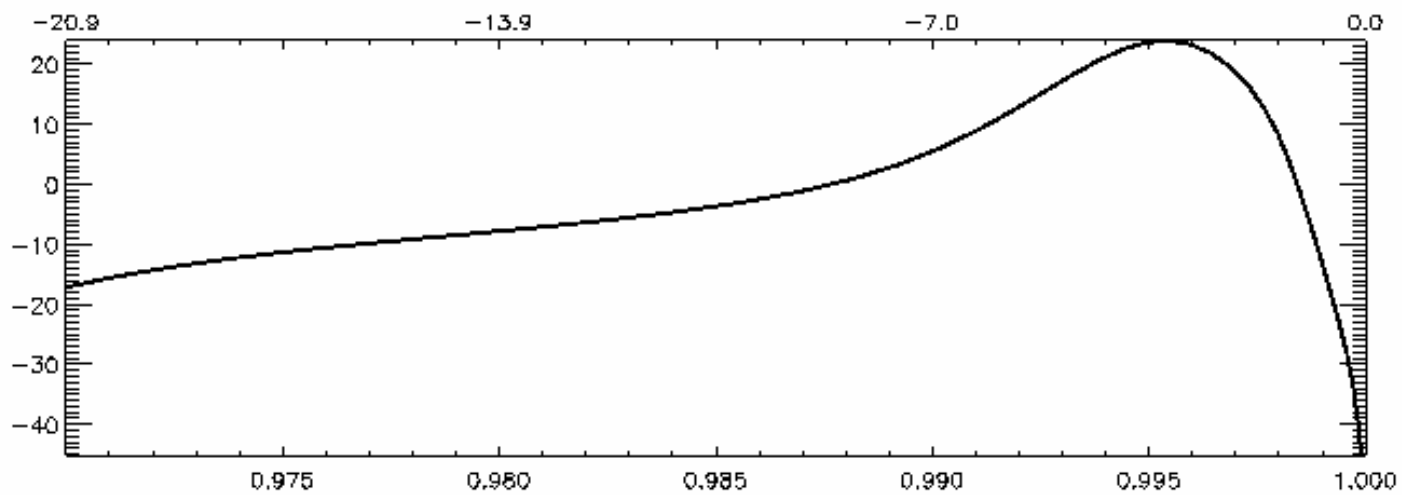
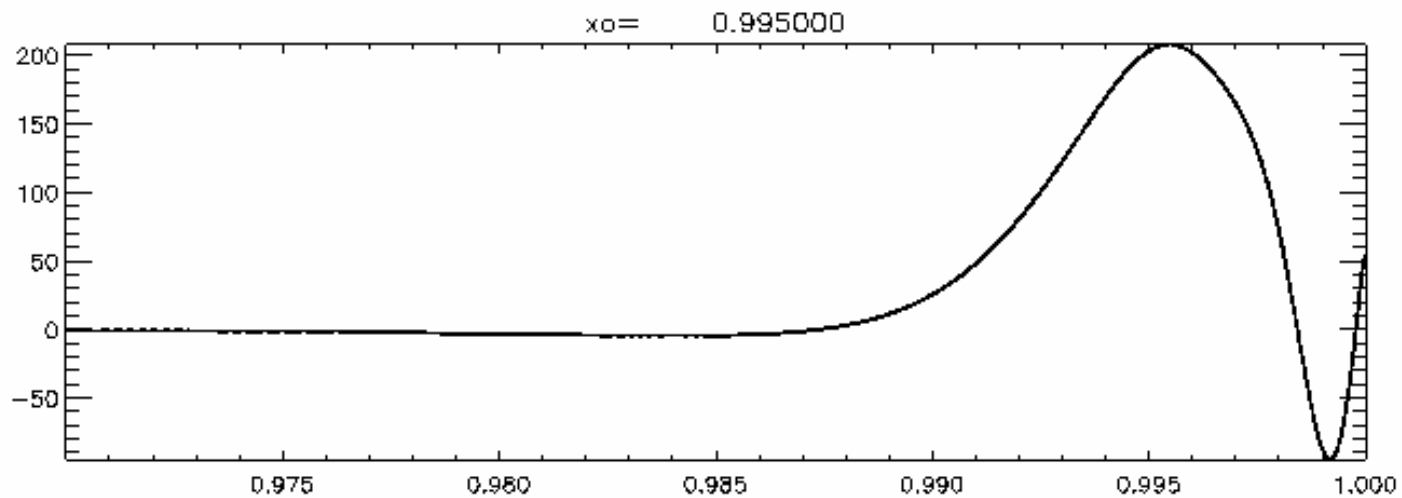






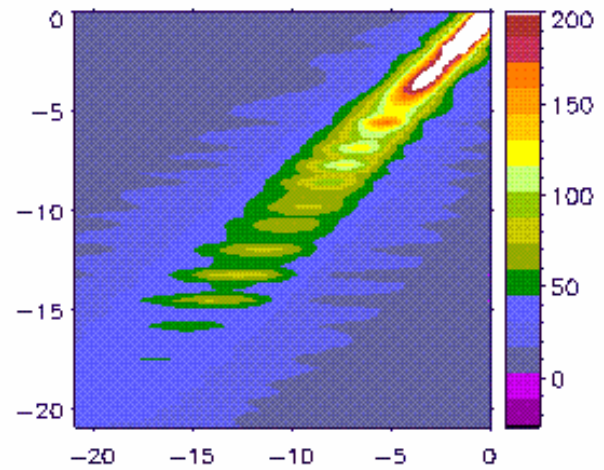
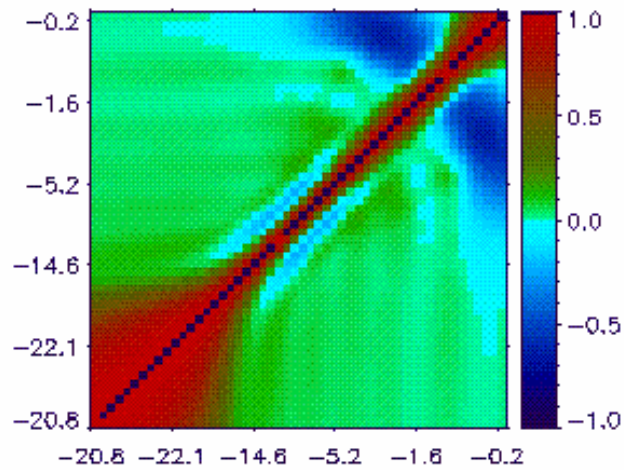
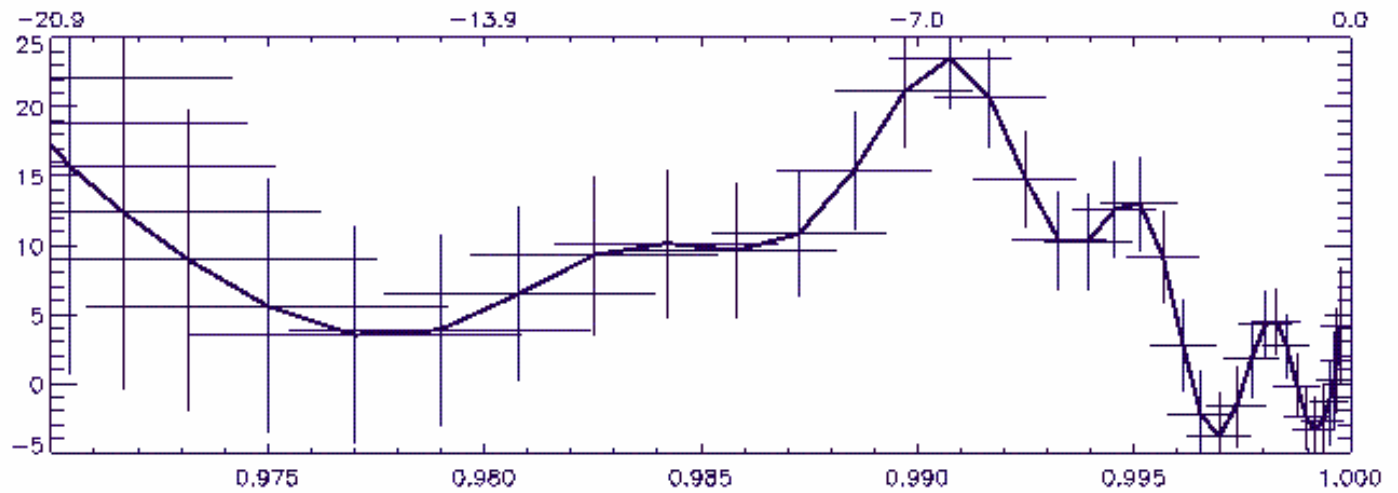


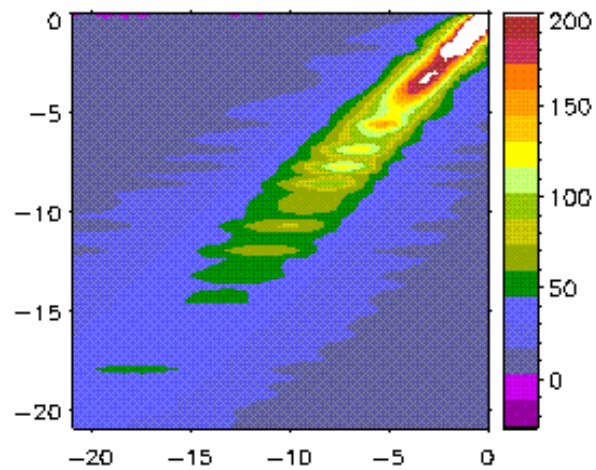
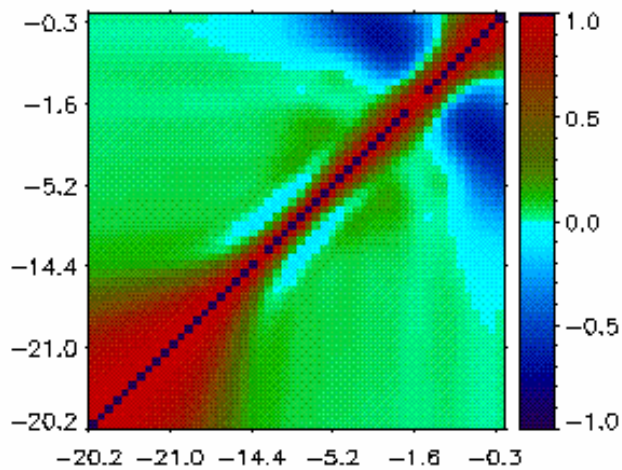
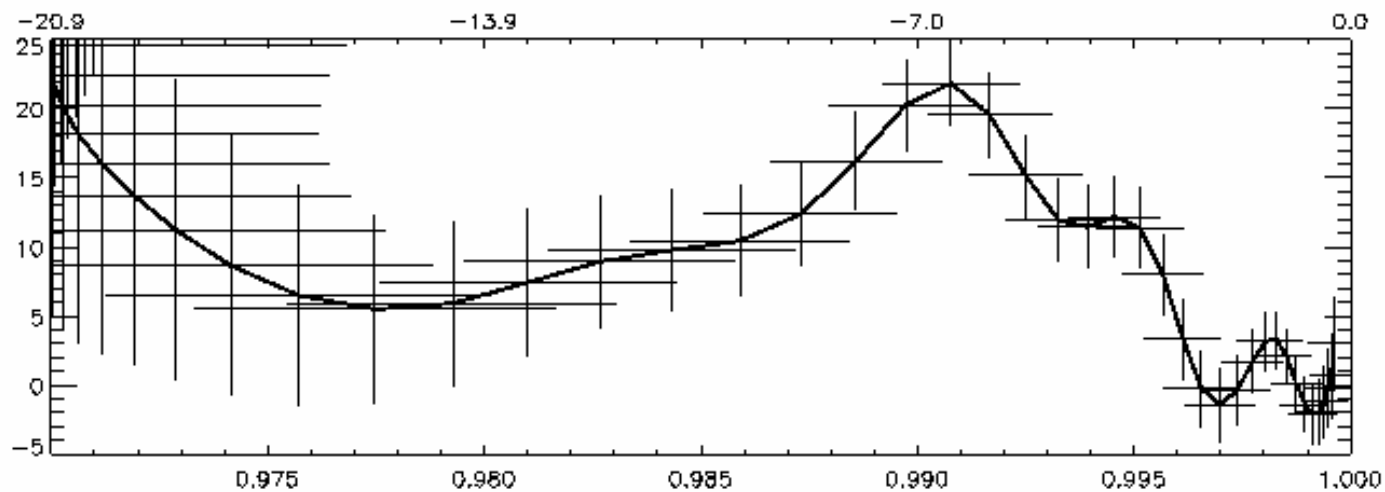




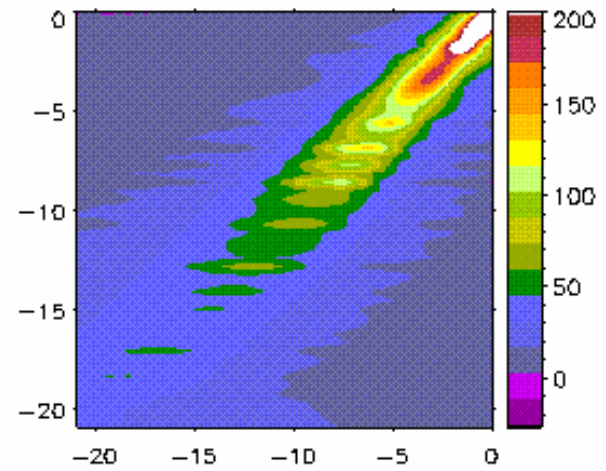
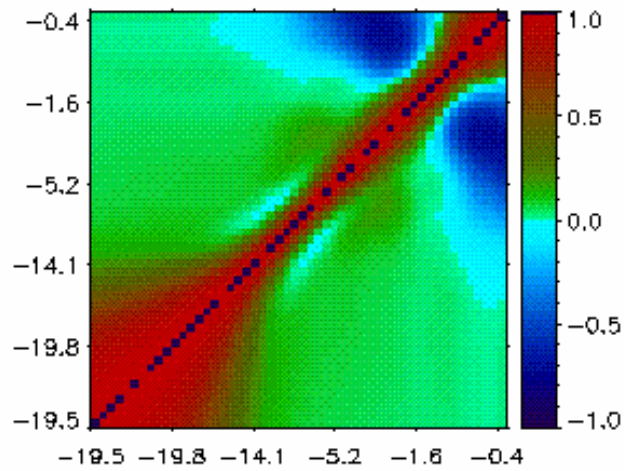
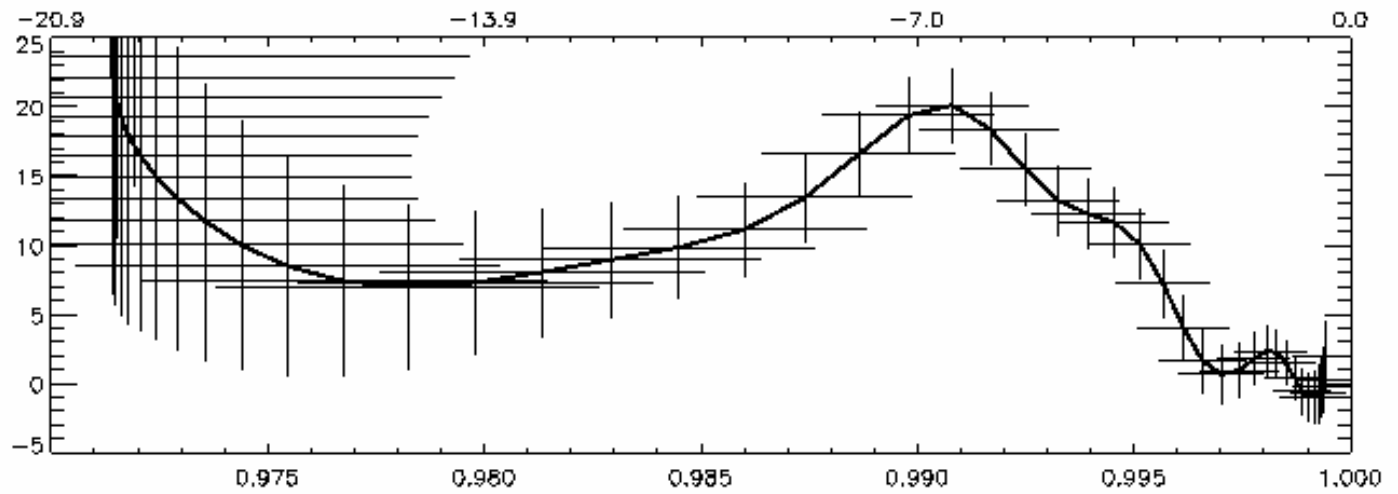
# What could be done?

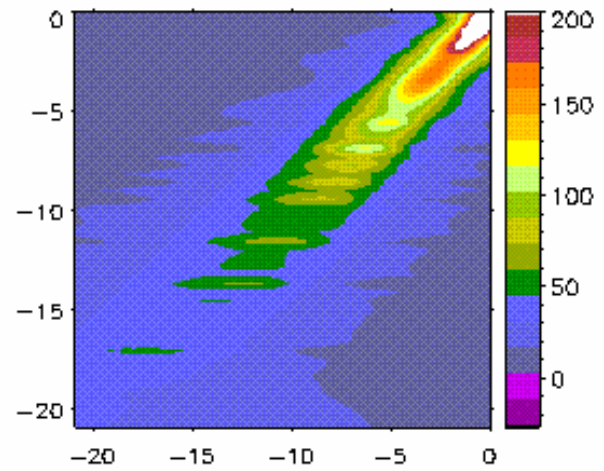
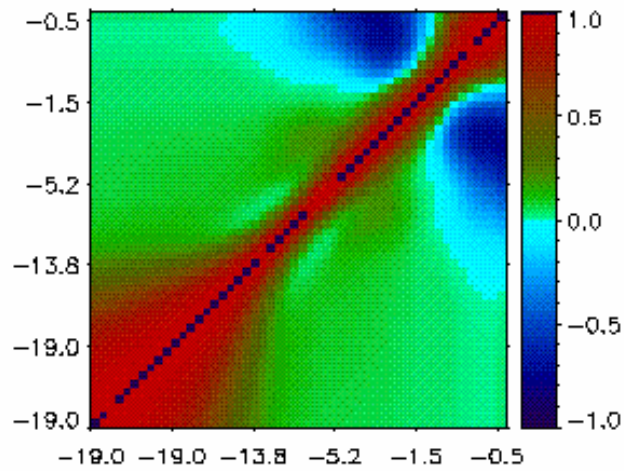
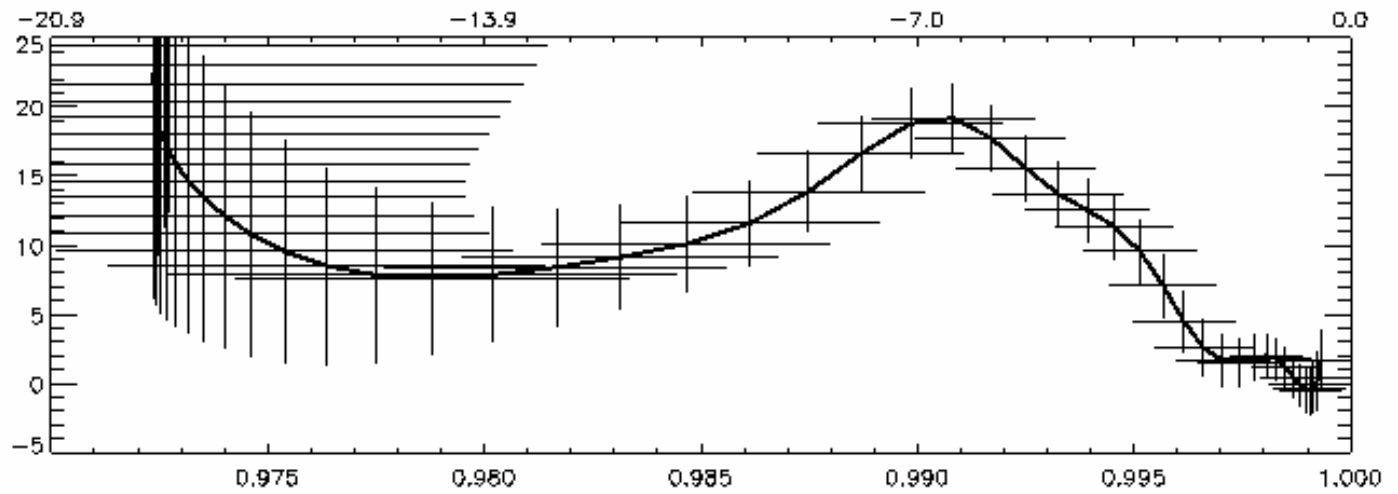
- Exploring the choice (automatic?) of the regularization parameter for different CMD
- Use other functional forms: spline, related to theories ...
- Use GSVD for RLS
  - Fast and more robust than solving normal equations
  - Solve quasi-simultaneously for a set of regularization parameters => automatic choices (L-curve, GCV) easier to implement
- Use OLA type of method
  - Allow different regularization for different depths
  - Easier to interpret in terms of resolution

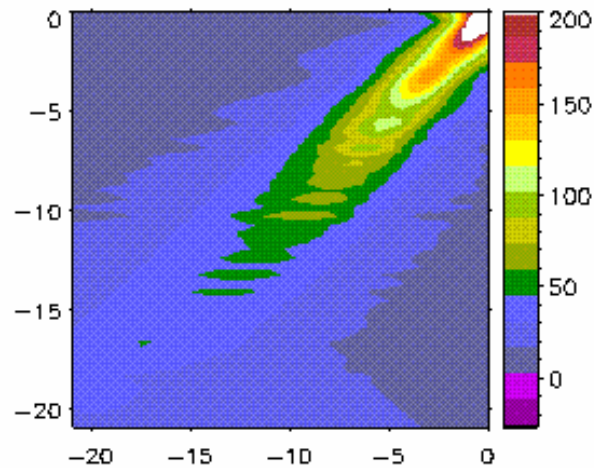
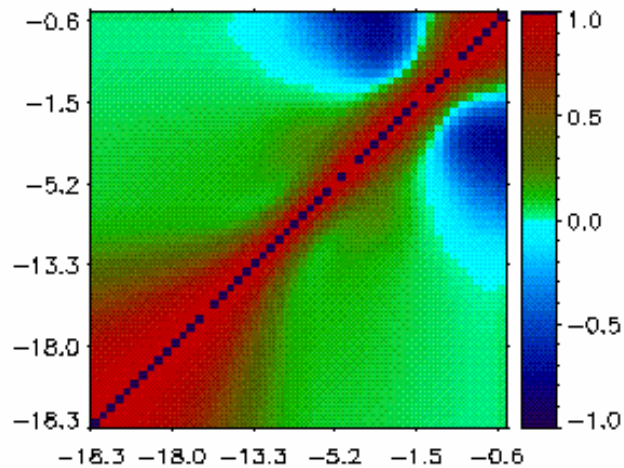
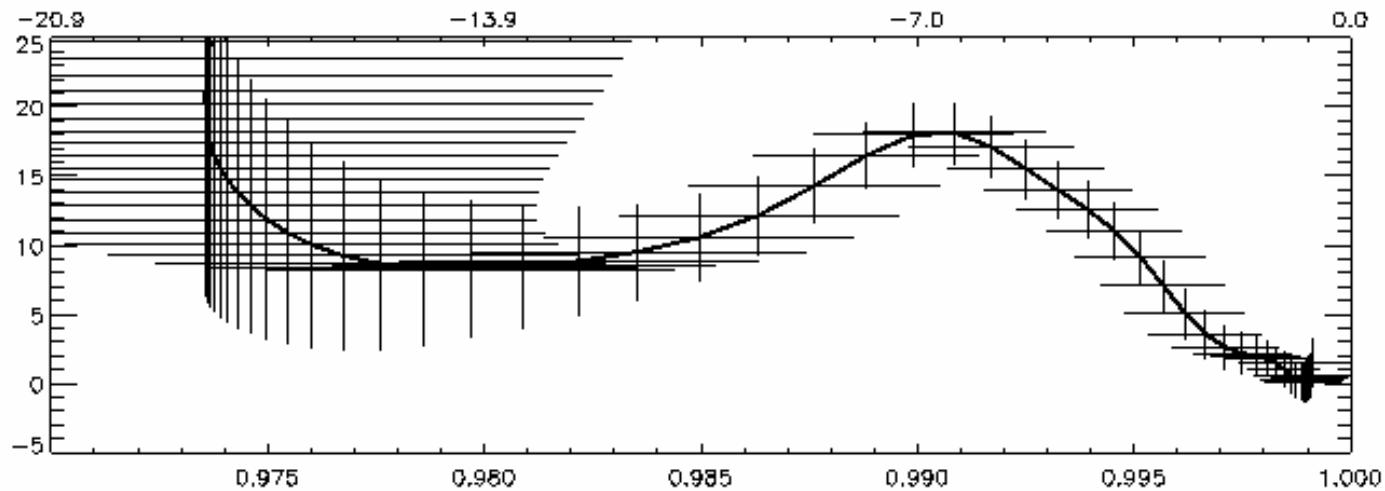


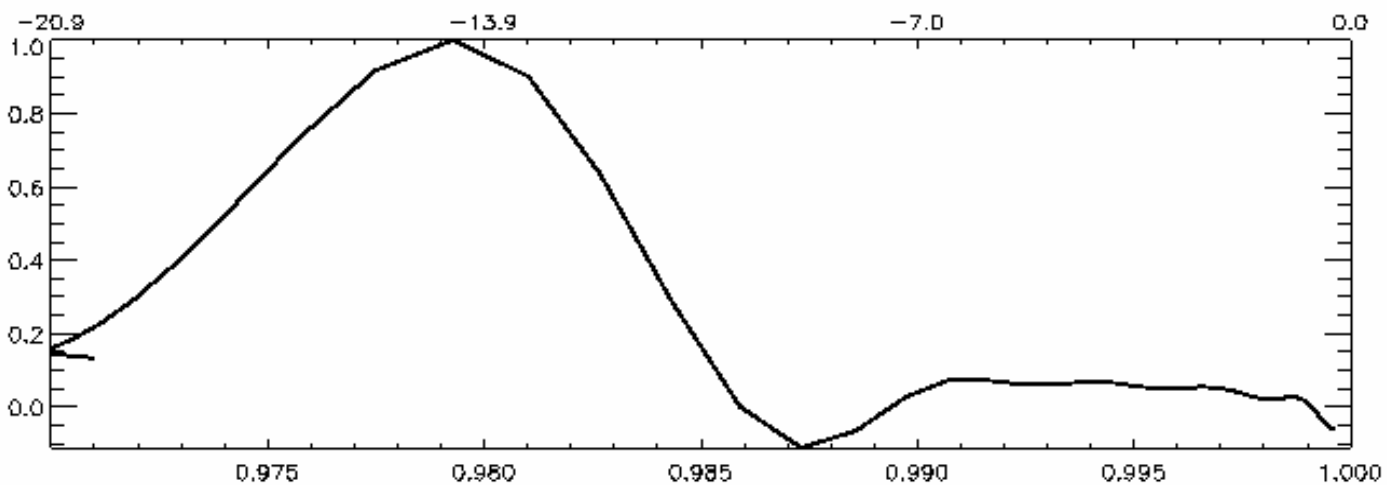
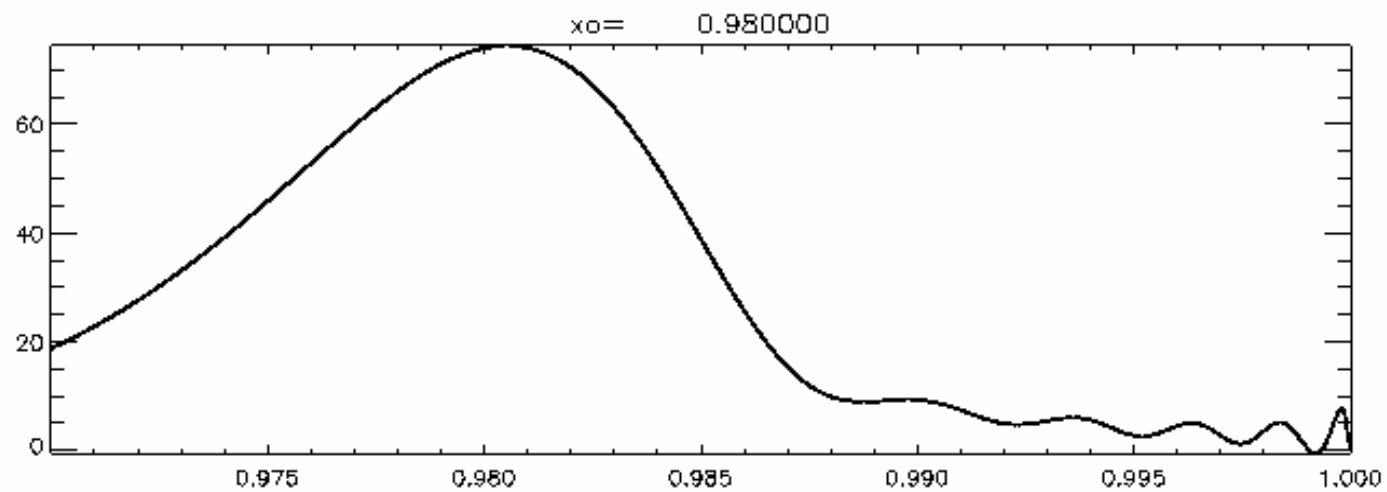


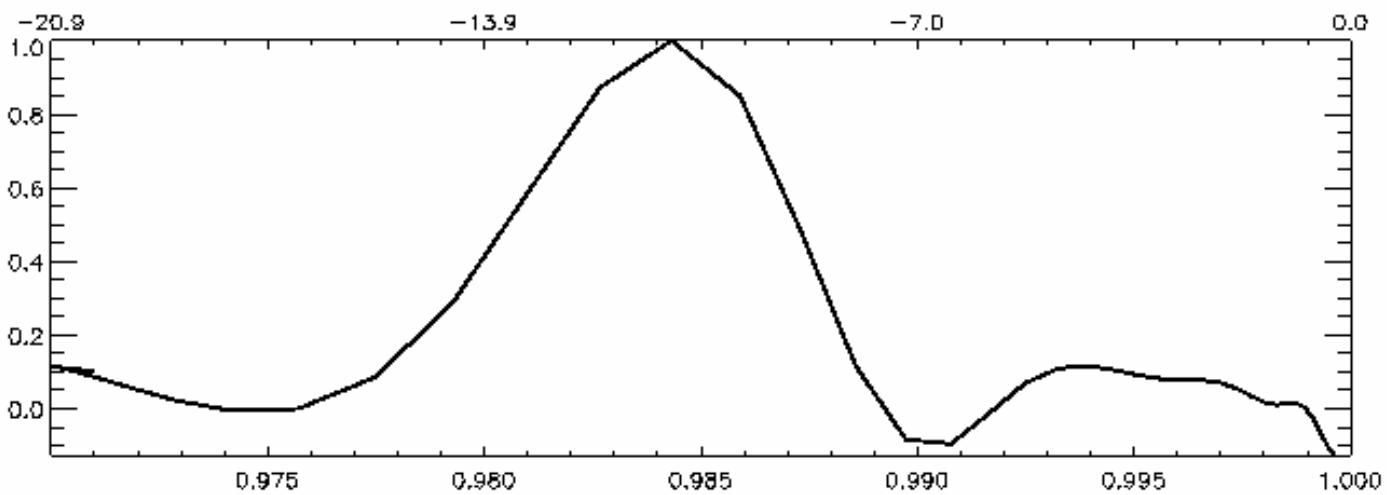
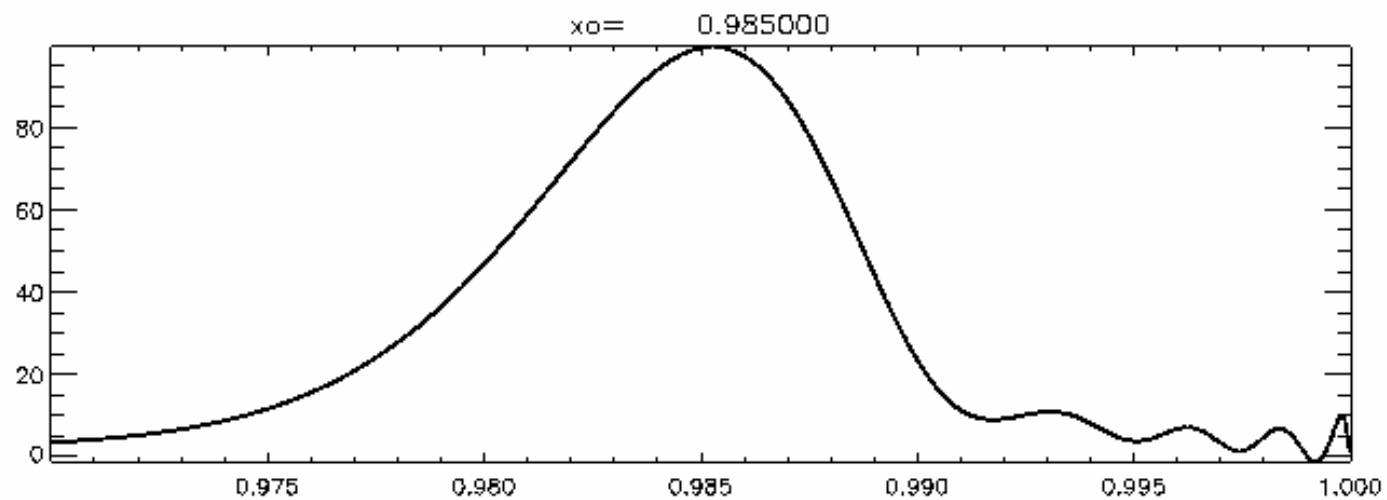


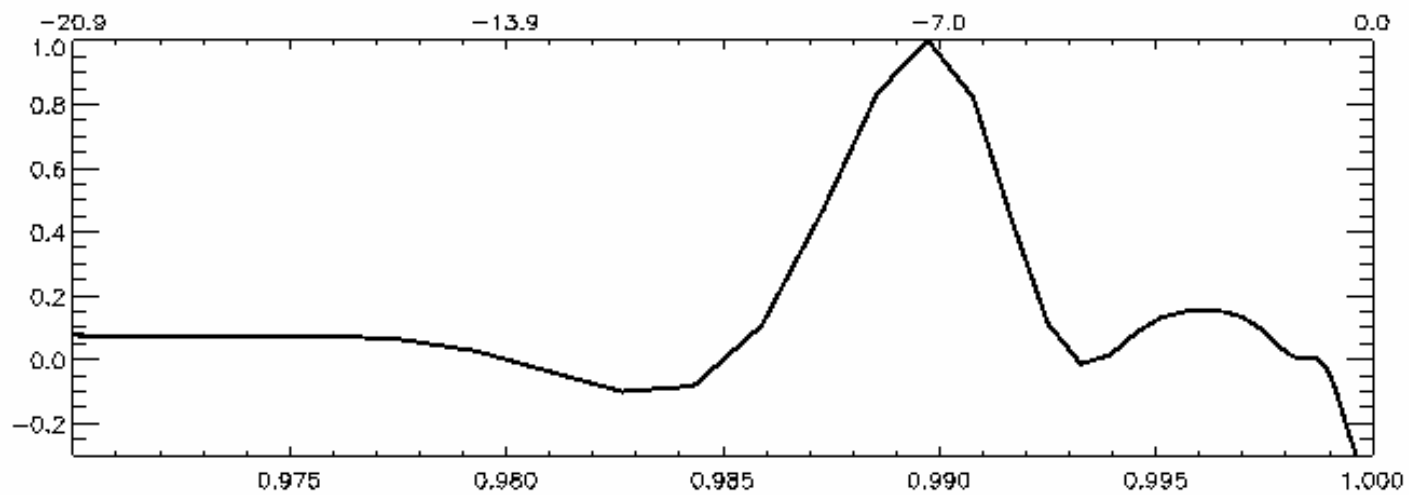
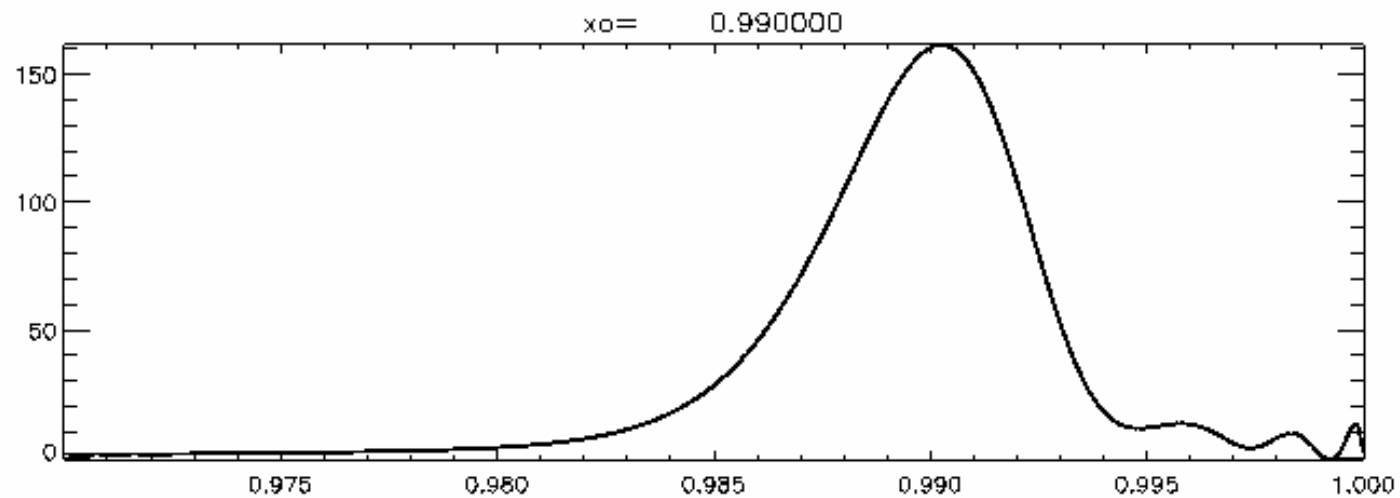


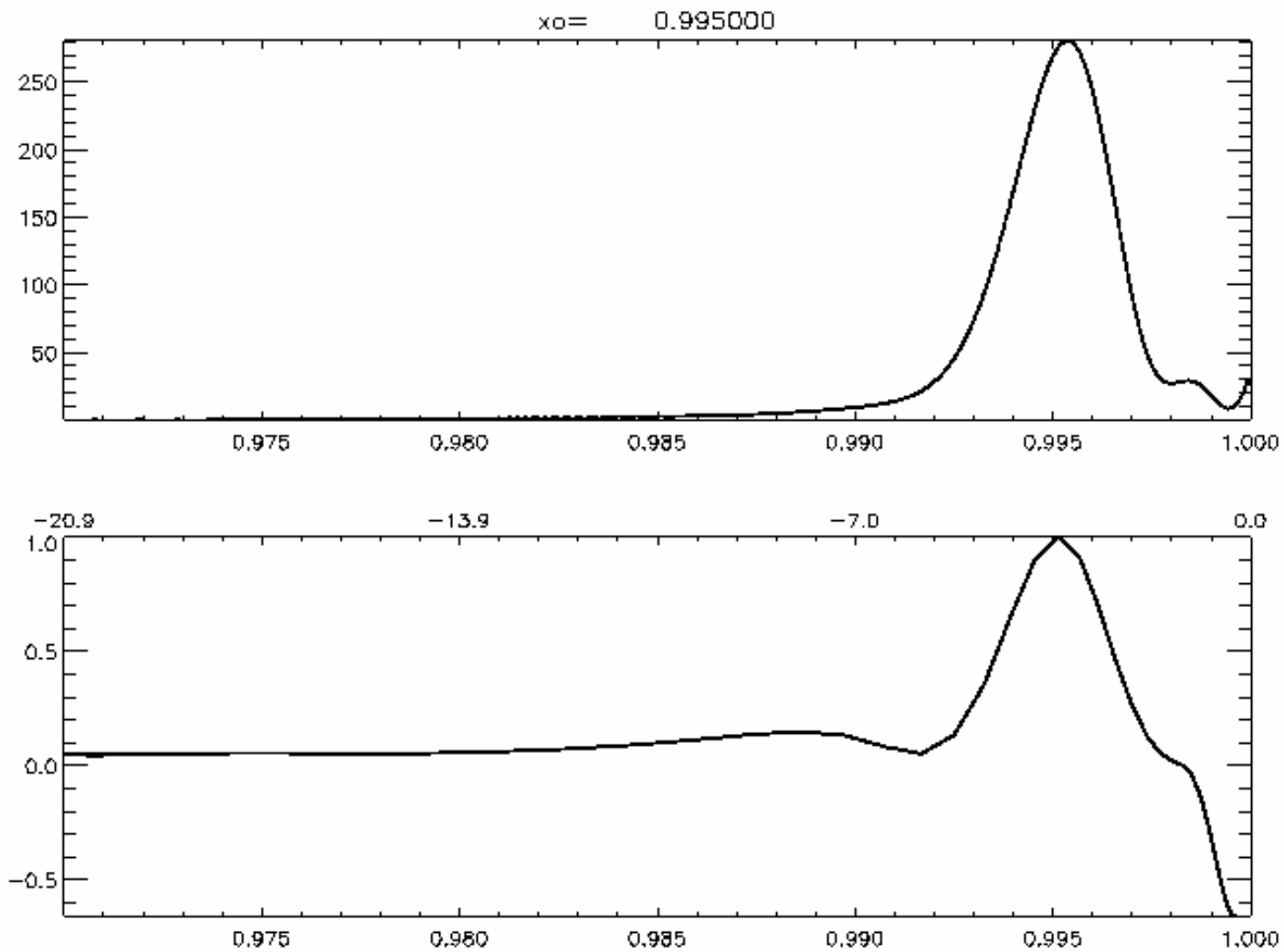












# Correlation Matrix

$$C_{\bar{\mathbf{v}}} = B_{\varepsilon}^{-1/2} B_{\bar{\mathbf{v}}} B_{\varepsilon}^{-1/2}$$

$$Cor(\bar{\mathbf{v}}_j, \bar{\mathbf{v}}_k) = \frac{\sum_i A_{ji} A_{ki} \sigma_i^2}{\sqrt{\sum_i A_{ji}^2 \sigma_i^2} \sqrt{\sum_i A_{ki}^2 \sigma_i^2}}$$

